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Concurso para a atribuição de Bolsas Individuais 2006

Grant proposal for individual study 2006

Aberto de 01-03-2006 a 31-03-2006

opened from 01-03-2006 to 31-03-2006

Referência

Reference

SFRH/BD/27272/2006

Data de registo

Registry date

Registado a 01-03-2006 (09:18)

Registered at 01-03-2006 (09:18)

Lacrado

Submitted

Lacrado a 14-04-2006 (14:07)

Submitted at 14-04-2006 (14:07)

Identificação do candidato

Candidate's personal information

Nome completo

Full name

Cristiana João Soares da Silva

Número de identificação fiscal (NIF)

Taxpayer identification number

219826021

Data de nascimento

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Naturalidade (Concelho)

Birth place

Batalha

Bilhete de identidade

National identity card No.

11765024(Emitido em26-06-2002)

País de Nacionalidade

Birth place

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Código postal

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Habilitações académicas

Academic degrees

Ano

Year

2005

Grau académico

Academical Degree

MESTRADO

Título da tese (se aplicável)

Thesis title (if applicable)

Abordagens do Cálculo das Variações e Controlo Ótimo ao Problema de Newton de Resistência Mínima

Domínio Científico

Scientific Domain

Matemática

Instituição que atribuiu o grau

Institution granting the academic degree

Universidade de Aveiro

Classificação

Classification

Aprovada (sistema binário: aprovado/reprovado)

Ano
Year
2003

Grau académico
Academical Degree
LICENCIATURA

Título da tese (se aplicável)
Thesis title (if applicable)

Domínio Científico
Scientific Domain
Matematica

Instituição que atribuiu o grau
Institution granting the academic degree
Universidade de Coimbra - Faculdade de Ciências e Tecnologia

Classificação
Classification
15

Actividades anteriores e situação actual em termos científicos e/ou profissionais
Previous and current scientific and/or professional activities

Período Period	Cargo ou categoria Position or category	Instituição Institution
2002-2003	Professora estagiária	Escola EB 2,3 Dr. José dos Santos Bessa
1 Fevereiro a 30 Abril de 2006	Bolseira da Fundacao Calouste Gulbenkian	Mathématiques, Labo. AN-EDP, UMR 8628 - Universite Paris-Sud XI - France

1. Informações sobre a candidatura
1. Application form information

Tipo de Bolsa
Type of Fellowship
Bolsa de Doutoramento
Doctoral Grant

Domínio Científico Principal
Main Scientific Domain
Matemática
Mathematics

Local de realização da Bolsa
Location of fellowship activities
Mista
Both in Portugal and Abroad

2. Endereço para correspondência
2. Mailing address information

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3. Procurador do candidato
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Observações
Notes

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4. Programa de trabalhos

4. Working programme

4.1. Título do programa de trabalhos

4.1. Title of the working programme

Optimal syntheses of nonlinear optimal control problems involving state constraints, and conjugate points

Domínio Científico

Scientific Domain

Mathematics, Optimal Control

Data de início do programa de trabalhos

Work programme starting date

01-10-2006

Duração (meses)

Duration (month)

48

Data de início pretendida para a bolsa

Fellowship starting date

01-10-2006

Duração (meses)

Duration (month)

48

Permanência no estrangeiro com início em

Periods of permanence abroad

01-10-2006

Duração (meses)

Duration (month)

9

01-10-2007

9

01-10-2008

9

01-10-2009

9

4.2. Sumário

4.2. Abstract

In optimal control problems, three main basic questions have to be answered (see e.g. [Torres'04]): Does an optimal solution exist? How can one restrict the candidates for optimality by way of necessary conditions? Is a candidate found in this way indeed optimal (in a local/global sense)? For the problem of existence of optimal trajectories, fairly general results are known (see e.g. [Lee,Markus'67]), which cover a wide range of realistic problem situations, involving any type of constraint. In contrast, theories of necessary and sufficient conditions for optimality lack a similar completeness of results. If state constraints are moreover imposed, the situation is widely open. The Pontryagin maximum principle [Pontryagin et al.'62] gives first order conditions for optimality, whenever there is no state constraint, or in the case of constraints of order one. For more general constraints, other maximum principles exist (see e.g. [Jacobson,Lele,Speyer'71], [Maurer'77]). However, in most cases, there exists a significant gap between the structure of extremals (i.e., trajectories that satisfy the necessary conditions for optimality) and the structure of optimal trajectories in an optimal synthesis. Our aim is to contribute in closing this gap.

4.3. Estado da Arte

4.3. State of the art

In the eighties, much progress has been made in closing the gap between necessary and sufficient conditions, in dimensions two and three, when there is no state constraint. The main results in that direction have been obtained in [Krener,Schattler'89], [Schattler'88], [Sussmann'87], and concern the qualitative structure of small-time reachable sets for autonomous control-affine systems. Later, with [Bressan,Piccoli'98] and [Piccoli'96], more precise results were obtained on two-dimensional manifolds (see also the book of [Boscain,Piccoli'04]). These results describe the small-time reachable sets, and hence, the local structure of optimal trajectories, in low dimensions, in function of the Lie bracket configuration of the vector fields that define the control system. For autonomous control-affine systems subject to a pure state constraint of the inequality type, the first (local) results appear in [Bonnard,Faubourg,Launay,Trélat'03]. They have been motivated by a concrete real-life optimal control problem.

4.4. Objectivos

4.4. Objectives

The main objectives of the proposed PhD project are four: (i) to extend the previously known results on the local structure of optimal trajectories, in dimensions two and three, to the case of higher-order dimensions (to investigate the existence of singular trajectories; occurrence of the Fuller phenomenon; etc); (ii) to obtain global results (to investigate the conjugate points along the extremal trajectories; etc); (iii) to extend the conjugate point theory for control systems subject to state constraints (to investigate the possibility of extending the classical Morse theory to quadratic forms defined on semi-spaces; to investigate necessary and/or sufficient second-order conditions for optimality; to investigate on a possible theory of envelopes; etc); (iv) to apply the obtained results to concrete optimal control problems with relevance in applications (to investigate efficient and stable numerical methods; etc).

4.5. Descrição detalhada

4.5. Detailed description

The first part of the PhD subject consists in going on with the results of [Bressan,Piccoli'98],[Bonnard,Faubourg,Launay,Trélat'03],[Torres'03],[Boscain,Piccoli'04], and, in particular, in extending the previously obtained results to the case of higher dimensions. The problem is challenging, because the structure of extremals can be extremely complicated, in particular due to the generic existence of singular trajectories, and to the occurrence of the Fuller phenomenon (see [Kupka'90]). On the other part, this question is crucial for the concrete applications of the optimal control theory, since it is an essential preliminary theoretical step in order to implement numerical methods (as the shooting method, see [Trélat'05]).

Once these local optimal syntheses have been determined, another very important question is to make them global. A usual tool to achieve this is the conjugate point theory. Roughly speaking, the first conjugate time along an extremal trajectory is the times at which the trajectory ceases to be optimal. However, up to now, the results of that theory (see for instance [Agrachev,Sachkov'04],[Ioffe,Tihomirov'79],[Sarychev'80], and [Sussmann'89]) concern the case where there does not exist any state constraint. No results exist when there are some state constraints. From the numerical point of view, the determination of conjugate points consists in testing a determinant computed from a variational system attached to the control system. Recently, efficient algorithms have been written, implementing this computation (see [Bonnard,Caillaud,Trélat'05], and the routine "cotcot", available on the web), that have been used for aeronautic control issues.

The second part of the PhD subject consists in developing the conjugate point theory for control systems submitted to state constraints. From the theoretical point of view, two approaches seem to be promising. First, one way is to extend the classical Morse theory to quadratic forms defined on semi-spaces, and to deduce necessary and/or sufficient second-order conditions for optimality, in the case of state constraints. Another approach is to adapt the theory of envelopes (see [Sussmann'89]) to the case of state constraints. Hence, the work is both theoretical, and numerical, since the obtained conditions then have to be implemented, and the software "cotcot" has to be extended to this framework.

4.6. Anexos

4.6. Attachments

4.7. Referências

4.7. References

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[Bonnard,Caillaud,Trélat'05] B. Bonnard, J.-B. Caillaud, E. Trélat, Cotcot: short reference manual, Technical report RT/APO/05/1, March 2005, <http://www.n7.fr/apo>

[Bonnard,Faubourg,Launay,Trélat'03] B. Bonnard, L. Faubourg, G. Launay, E. Trélat, Optimal control with state constraints and the space shuttle re-entry problem, J. Dynam. Cont. Syst. 9(2), 2003, 155-199.

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[Kupka'90] I. Kupka, The ubiquity of Fuller's phenomenon, Nonlinear controllability and optimal control, Monogr. Textbooks Pure Appl. Math. 133, Dekker, New York, 1990, 313-350.

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[Pontryagin et.al.'62] L. S. Pontryagin, V. G. Boltyanskii, R. V.

Gamkrelidze and E. F. Mishchenko, The mathematical theory of optimal processes, Interscience Publishers John Wiley and Sons, Inc., New York-London, 1962.

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[Sussmann'87] H. J. Sussmann, The structure of time-optimal trajectories for single-input systems in the plane: the C infinity nonsingular case, SIAM J. Control Optim. 25(2), 1987, 433-465.

[Sussmann'89] H. J. Sussmann, Envelopes, high-order optimality conditions and Lie brackets, Proceedings of the 28th IEEE Conference on Decision and Control, Vol. 1-3 (Tampa, FL, 1989), 1107-1112, New York, 1989.

[Torres'03] D. F. M. Torres, Lipschitzian regularity of the minimizing trajectories for nonlinear optimal control problems. Math. Control Signals Systems 16 (2003), no. 2-3, 158-174.

[Torres'04] D. F. M. Torres, Carathéodory equivalence, Noether theorems, and Tonelli full-regularity in the calculus of variations and optimal control, J. Math. Sci. (N. Y.) 120 (2004), no. 1, 1032-1050.

[Trélat'05] E. Trélat, Optimal control: theory and applications, Vuibert, 2005 (in French).

5. Condições de acolhimento

5. Host conditions

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Nationality of the institution granting the academic degree
Portuguesa / Portuguese

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Institution granting the academic degree
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Nome**Name**

Professor Doutor Alexander Plakhov

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Nome**Name**

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Nome**Name**

Professor Doutor Guy David

Instituição**Institution**

Directeur du Laboratoire de Mathématique, Bat. 425, UMR 8628, Univ. Paris-Sud, Orsay

7. Bolsas anteriores**7. Previous fellowships****Ano de conclusão Ref. da Bolsa****Year of completion Fellowship Ref.**

2006

Bolsa de estudo de curta duracao no estrangeiro - sob a orientação do Prof. Doutor Emmanuel Trélat

Instituição**Institution**

Fundacao Calouste Gulbenkian

Período**Period**

De 1 de Fevereiro a 30 de Abril de 2006

Ano de conclusão Ref. da Bolsa**Year of completion Fellowship Ref.**

2005

Bolsa de Mestrado

Instituição**Institution**

Fundacao Calouste Gulbenkian

Período**Period**

2003-2005

Ano de conclusão Ref. da Bolsa**Year of completion Fellowship Ref.**

2003

Bolsa a estudantes do ensino secundario e superior

Instituição

Institution
Fundacao Calouste Gulbenkian
Período
Period
1997-2003

8. Actividade Profissional
8. Professional activity

Tenciona manter alguma actividade profissional durante o período da bolsa?
Do you intend to maintain any professional activity during the fellowship period?

Não
No



Financiamento do Fundo Social Europeu e de fundos nacionais do MCTES



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